New Mesocyclone Detection Algorithm

-Training Module-

2019 HWT EWP – Satellite & Radar Experiment









New Mesocyclone Detection Algorithm (NMDA) - Background

- Tasked by the NWS Radar Operations Center (ROC) to modernize the suite of WSR-88D single-radar severe weather algorithms
- Construct a new "engine" for the current MDA within the WSR-88D ORPG
- Utilizes single-radar velocity-derived azimuthal shear (AzShear) product as the main catalyst for creating detections
- Development and testing within WDSS-II (backbone of MRMS)
- Displayed within AWIPS-II utilizing the current MD framework

NMDA – Technical Details (1/2)

Uses 6 products to detect and track

- Main: AzShear (main catalyst), Smoothed Shear Diameter, & Smoothed Velocity
 Difference
- Quality Control: *Reflectivity & Spectrum Width*
- Tracking: Rapid Refresh (RAP) derived Sounding Table (0-6 km storm rel. motion)



NMDA – Technical Details (2/2)

Step 1: Creates 2D detections (each tilt)

- 1. Initial Objects: AzShear > 0.006 | Shear Diameter >= 2 km | Delta-V >= 5 km
- 2. AzShear Maximums of Initial Objects (could be multiple maximums per object QLCS)
- 3. QC using SPW/REF ratio -&- Proximity Check To Other Maximums (*shear diameter*)

Step 2: Creates 3D detections from 2D detections

- At end of volume -or- with each new SAILS cut (MRLE still under development)
- All 3D detections must be at least three 2D detections in height, except:
 - if SAILSx3 and first cut occurs after 0.9° -or- 3D detection is > 100 km from radar
- All 2D detections used must be below 8 km in height

Step 3: Tracks 3D detections between volumes and SAILS cuts

- Uses only the RAP derived 0-6 km storm relative motive for tracking
- Past 3D detections stored in memory for 10 minutes \rightarrow in case radar error or range folding

NMDA – Performance Notes

- Just like the current MDA, can identify mesocyclones and track with time
- Only tracks cyclonic rotation (anti-cyclonic under development)
- Integrates SAILS (MRLE still under development)
- Caveats:
 - Identification and tracking of some QLCS circulations (small diameter and shallow)
 - Occasional false detections within high-velocity stratiform rain fields
 - If a circulation is large, a neighborhood check to remove multiple detections of the same area of rotation will sometimes remove nearby detections of independent rotation

NMDA - Evaluation

- Evaluation:
 - Compare NMDA to the existing MDA products Mesocyclone (MD) and Digital Mesocyclone (DMD) – within the AWIPS-II environment
- NMDA products will be under the "EWP" header on the AWIPS-II toolbar
 - Each radar will have the MD, DMD, and NMDA grouped together for easy access to all three
 - NMDA will be listed as "X---", with the three dashed representing the three letter radar identifier

NMDA – AWIPS-II Visualization



Uses the existing structure of MD product for AWIPS-II visualization

3 Different Icons → Uses part of existing MD icons

- Thin Circle
 - Strength Rank < 5
- Thick Circle
 - Strength Rank >= 5
 - <u>Height > 1 km ARL -&- Base of</u>
 <u>Detection NOT on Lowest Tilt</u>
- Thick Circle w/ Spikes
 - Strength Rank >= 5
 - Height <= 1 km ARL -or- Base of Detection ON Lowest Tilt

Increase magnification and change color to more easily view NMDA icons and the detection table.

NMDA – AWIPS-II Detection Table

	• • • • •	Conversion tables
Circulation ID (<i>CIR</i>)	0 - 999	information ir
SCIT ID (STMID)	None (always A0)	CIR STMID 39 A
Strength Rank (SR)	1 - 25 <u>AzShear Val (s⁻¹) SR</u> 0.006 - 0.0069 1 0.007 - 0.0079 2 0.008 - 0.0089 3 0.028 - 0.029 24 >= 0.03 25	SR LLRV 1 AZ RAN 32 HGT MXRV 6 BASE OPTH 6 Height of Maximum Rotation (HGT) Maximum Rotation Value (MXRV)
Low Level Rotation Value (LLRV)	AzShear (s ⁻¹) * 1000	
	0.006 = 6 0.01 = 10	Height of Detection Base (BASE)
Radar Azimuth (AZ)	Degrees (same as MD)	Depth of Detection (<i>DPTH</i>)
Range from Radar (RAN)	Nautical Miles (same as MD)	** Will be zero if detection

Conversion tables to decipher detection information in the NMDA Table



Height of Maximum Rotation (<i>HGT</i>)	Kilofeet (same as MD)
Maximum Rotation Value (<i>MXRV</i>)	AzShear (s ⁻¹) * 1000 Same conversion as LLRV
Height of Detection Base (BASE)	Kilofeet (same as MD)
Depth of Detection (<i>DPTH</i>) **	Kilofeet (same as MD)

* Will be zero if detection is just one 2D detection deep

NOTE: If more than 6 detections are present, center click the loaded product name in the AWIPS-II display to cycle detections through the table.